

Symmetries of the interacting boson model

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This contribution reviews the symmetry properties of the interacting boson model of Arima and Iachello. While the concept of a dynamical symmetry is by now a familiar one, this is not necessarily so for the extended notions of partial dynamical symmetry and quasi dynamical symmetry, which can be beautifully illustrated in the context of the interacting boson model. The main conclusion of the analysis is that dynamical symmetries are scarce while their partial and quasi extensions are ubiquitous.

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1 Introduction

In 1975 Arima and Iachello proposed a new approach to nuclear collective motion, the interacting boson model or IBM [1]. It quickly became a popular model for the interpretation of nuclear data and acquired the center stage of discussions within the nuclear-structure community in the remainder of the decade and much of the 1980s.

What made and still makes the model so appealing? One of its strengths is that it offers a unified view of several descriptions which until the 1970s existed more or less separately. Nuclei can be viewed as incompressible, charged liquid drops, which vibrate and, if deformed, also

rotate [2, 3]. From this picture are derived a variety of models such as the anharmonic spherical vibrator [4], the deformed rotor-vibrator [5], or the γ -unstable rotor [6]. The IBM includes all three descriptions as special cases of its Hamiltonian. Not only do such cases turn out to be analytically solvable through the use of dynamical symmetries but, in addition, one may easily interpolate in the IBM between the different geometric solutions.

A second advantage of the IBM concerns its connection with the nuclear shell model. Although originally proposed as purely phenomenological description of nuclei, it was realized early on that a microscopic justification can be obtained by considering the bosons as pairs of valence nucleons with angular momentum $L = 0$ or $L = 2$ [7, 8]. The model therefore has acquired a status that is intermediate between phenomenological collective and more microscopic single-particle models. This shell-model interpretation of the IBM also showed the direction of various extensions, extendibility being another one of its strong points. Given the interpretation of the bosons as pairs of nucleons, it was soon suggested that bosons should come in two varieties, neutron and proton, giving rise to the IBM-2 [9]. Furthermore, Elliott and co-workers [10, 11] pointed out that the existence of corresponding symmetries in the interacting boson model and in the nuclear shell model can be put to good use in the microscopic justification of the former.

But perhaps the most characteristic aspect of the IBM is its symmetry-based formulation. Symmetries, of central importance to physics, also play a pivotal role in the IBM, which makes in particular extensive use of the no-

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tion of dynamical symmetry. While the latter might still be unfamiliar as a term, it appears in diverse areas of physics, also in nuclear physics where it received widespread attention. Notable examples are Wigner's supermultiplet model [12], Racah's pairing model [13, 14], and Elliott's rotation model [15, 16], and their many extensions that can be formulated in terms of dynamical symmetries [17, 18].

It is not the aim of this contribution to give a comprehensive review of the properties of the IBM but rather to focus on the use of notions of symmetry in the model. It specifically deals with two further generalizations of the concept of dynamical symmetry, which have been developed over the last two decades, namely partial dynamical symmetry and quasi dynamical symmetry. Again, the IBM proved to be instrumental in the development of these novel symmetry notions and the basic ideas behind these extensions can be illustrated beautifully with a simplified IBM Hamiltonian [19]. Before turning to these extended notions of symmetry, a brief review of the IBM is given.

2 The interacting boson model

2.1 Basic properties

In the original version of the IBM as applied to even-even nuclei, collective properties of the nucleus are described in terms of a set of interacting s and d bosons carrying the angular momenta $\ell = 0$ and $\ell = 2$, respectively. In the simplest version of the model, referred to as IBM-1, it is assumed that there is only one kind of boson (i.e., no distinction is made between neutron and proton bosons) and that they carry no further intrinsic labels such as spin or isospin. The associated creation and annihilation operators satisfy the standard boson commutation relations

$$\begin{aligned} [b_{\ell m}, b_{\ell' m'}^\dagger] &= \delta_{\ell\ell'} \delta_{mm'}, \\ [b_{\ell m}, b_{\ell' m'}] &= [b_{\ell m}^\dagger, b_{\ell' m'}^\dagger] = 0. \end{aligned} \quad (1)$$

The IBM-1 assumes that low-lying collective states of an even-even nucleus can be described in terms of boson excitations acting upon a vacuum state $|0\rangle$, which is interpreted as the doubly-closed core of the nucleus under consideration. There are six basic excitations, $s^\dagger|0\rangle$ and $d_m^\dagger|0\rangle$, $m = 0, \pm 1, \pm 2$, and the unitary transformations among them generate the Lie algebra $U(6)$. A different way of expressing the same property is through the construction of the bilinear operators $b_{\ell m}^\dagger b_{\ell' m'}$, which generate $U(6)$ [17].

As mentioned in the introduction, the bosons are associated with (collective) pairs of nucleons in the valence shell. Because of this interpretation, a collective state of

an even-even nucleus with $2N_b$ valence nucleons is approximated as a state with N_b bosons. In general, the separate boson numbers n_s and n_d are not conserved but the sum $n_s + n_d = N_b$ is. The Hamiltonian of the IBM-1 can therefore be written in terms of the generators of the Lie algebra $U(6)$ and acquires the generic form

$$\hat{H} = E_0 + \hat{H}_1 + \hat{H}_2 + \hat{H}_3 + \dots, \quad (2)$$

where the index refers to the order of the interaction in the generators of $U(6)$. The first term E_0 is a constant and represents the (negative of the) binding energy of the doubly-closed core. The second term is the one-body part

$$\begin{aligned} \hat{H}_1 &= \epsilon_s [s^\dagger \tilde{s}]^{(0)} + \epsilon_d \sqrt{5} [d^\dagger \tilde{d}]^{(0)} \\ &= \epsilon_s s^\dagger \cdot \tilde{s} + \epsilon_d d^\dagger \cdot \tilde{d} \equiv \epsilon_s \hat{n}_s + \epsilon_d \hat{n}_d, \end{aligned} \quad (3)$$

where the coupling in angular momentum is shown as an superscript in round brackets and the dot indicates a scalar product. Furthermore, $\tilde{b}_{\ell m} \equiv (-)^{\ell-m} b_{\ell, -m}$ and the coefficients ϵ_s and ϵ_d are the single-boson energies in the s and d state, respectively. The third term in the Hamiltonian (2) is the two-body interaction,

$$\hat{H}_2 = \sum_{\ell_1 \leq \ell_2, \ell'_1 \leq \ell'_2, L} \tilde{v}_{\ell_1 \ell_2 \ell'_1 \ell'_2}^L [b_{\ell_1}^\dagger b_{\ell_2}^\dagger]^{(L)} \cdot [\tilde{b}_{\ell'_2} \tilde{b}_{\ell'_1}]^{(L)}, \quad (4)$$

where the coefficients $\tilde{v}_{\ell_1 \ell_2 \ell'_1 \ell'_2}^L$ are related to the interaction matrix elements between normalized two-boson states,

$$\tilde{v}_{\ell_1 \ell_2 \ell'_1 \ell'_2}^L = (-)^L \frac{\langle \ell_1 \ell_2; L | \hat{H}_2 | \ell'_1 \ell'_2; L \rangle}{\sqrt{(1 + \delta_{\ell_1 \ell_2})(1 + \delta_{\ell'_1 \ell'_2})}}. \quad (5)$$

The bosons are symmetrically coupled and allowed two-boson states are: s^2 with angular momentum $L = 0$, sd with $L = 2$, and d^2 with $L = 0, 2, 4$. This leads to seven independent two-body interactions: three for $L = 0$, three for $L = 2$, and one for $L = 4$.

This analysis can be extended to higher-order interactions. The number of possible interactions at each order n is summarized in Table 1 up to $n = 3$. Some of these interactions contribute to the binding energy but do not influence the excitation spectrum of a nucleus, as indicated with "BE" in the table. The remaining interactions, listed under " E_x ", affect also the relative energies of the eigenstates.

2.2 Geometric interpretation

Before entering the discussion of symmetries, a brief discussion of the geometric interpretation is in order, which can be obtained by means of coherent (or intrinsic) states [20–22]. For the IBM-1 the coherent state is

Table 1 Number of n -body interactions in IBM-1.

Order	Number of interactions		
	Total	Type BE ^a	Type E_x^a
$n = 0$	1	1	0
$n = 1$	2	1	1
$n = 2$	7	2	5
$n = 3$	17	7	10

^aSee text for explanation.

of the form

$$|N_b; \alpha_\mu\rangle \propto \Gamma(\alpha_\mu)^{N_b} |0\rangle, \tag{6}$$

where α_μ are five complex variables in the expression

$$\Gamma(\alpha_\mu) = s^\dagger + \sum_{\mu=-2}^{+2} \alpha_\mu d_\mu^\dagger. \tag{7}$$

The α_μ have the interpretation of quadrupole shape variables and their associated conjugate momenta, analogous to those introduced in the droplet model of the nucleus [2, 3, 5]. The real part of the α_μ can be related to three Euler angles $\{\theta, \psi, \phi\}$, which define the orientation of an intrinsic frame of reference, and two variables, β and γ , that parametrize the intrinsic shape of the nuclear surface. In terms of the latter variables the state (7) is rewritten as

$$\Gamma(\beta, \gamma) = s^\dagger + \beta \left[\cos \gamma d_0^\dagger + \sqrt{\frac{1}{2}} \sin \gamma (d_{-2}^\dagger + d_{+2}^\dagger) \right]. \tag{8}$$

The calculation of the expectation value of an operator in the coherent state (6) leads to a function of N_b , β , and γ . The IBM-1 Hamiltonian (2) can be converted in this way into a total-energy surface $E(\beta, \gamma; N_b, \epsilon, \tilde{v}, \dots)$, where $\epsilon, \tilde{v}, \dots$ is a short-hand notation for the complete set of parameters in the Hamiltonian.

The study of the energy surface $E(\beta, \gamma; N_b, \epsilon, \tilde{v})$ has improved our understanding of the properties of the IBM-1 in two important ways. First, it was instrumental in showing that the three symmetry limits of the model, to be discussed below, have counterparts that are also known from the geometric model of the nucleus [23]. Establishing the correspondence between the IBM and the geometric model was, in fact, one of the major achievements in the early days of the model [20–22]. Secondly, the energy surface was studied from the point of view of catastrophe theory [24], with the single-boson energies ϵ and boson-boson interactions \tilde{v} viewed as control parameters that determine the minima, saddle points etc. of $E(\beta, \gamma; N_b, \epsilon, \tilde{v})$. This problem was worked out for the most general IBM-1 Hamiltonian with up to two-body interactions [25] and also in the context of the classical

Landau theory of phase transitions [26, 27]. It has given rise in recent years to a flurry of activity, which can be characterized as the study of quantum phase transitions in nuclei (see, e.g., the review [28]).

2.3 Dynamical symmetries

The numerical solution of the eigenvalue problem associated with the IBM-1 Hamiltonian (2) can be obtained in all cases of interest, that is, for values of N_b corresponding to numbers of valence pairs occurring in nuclei and for up to three-body interactions between the bosons. In addition, the interacting-boson problem can be solved analytically for certain boson energies and boson-boson interactions, and these solutions and their associated group-theoretical properties are by now well understood [29]. Three different analytical solutions (also known as “limits”) exist: the vibrational U(5) [30], the rotational SU(3) [31], and the γ -unstable SO(6) limit [32]. They can be summarized in a lattice of algebras of the form

$$U(6) \supset \left\{ \begin{array}{l} U(5) \supset SO(5) \\ SU_\pm(3) \\ SO_\pm(6) \supset SO(5) \end{array} \right\} \supset SO(3). \tag{9}$$

The algebras SU(3) and SO(6) have two different realizations depending on phase choices for the s and d bosons [33], as indicated by the \pm subscripts. In the following both algebras SU $_{\pm}$ (3) are considered — they correspond prolate and oblate shapes — whereas only SO $_{+}$ (6) is needed, henceforth denoted as SO(6).

The interpretation of the lattice (9) is as follows. If the Hamiltonian can be written in terms of Casimir operators associated with a chain of nested algebras, then the eigenvalue problem can be solved analytically, the quantum numbers associated with the different algebras are conserved, and eigenfunctions are independent of the parameters in the Hamiltonian. The underlying reason is that the Hamiltonian in that case can be written as a sum of commuting operators and that, as a consequence, the associated quantum numbers are conserved. The three limits can therefore be summarized with a chain of nested algebras and their associated quantum numbers. For the IBM-1 they are

$$\begin{array}{cccccc} U(6) \supset U(5) \supset SO(5) \supset SO(3) \supset SO(2) & & & & & \\ \downarrow & \downarrow & \downarrow & \downarrow & \downarrow & \\ [N_b] & n_d & v & \nu_\Delta L & M & \\ U(6) \supset SU_\pm(3) \supset SO(3) \supset SO(2) & & & & & \\ \downarrow & \downarrow & \downarrow & \downarrow & \downarrow & \\ [N_b] & (\lambda_\pm, \mu_\pm) & KL & M & & \\ U(6) \supset SO(6) \supset SO(5) \supset SO(3) \supset SO(2) & & & & & \\ \downarrow & \downarrow & \downarrow & \downarrow & \downarrow & \\ [N_b] & \sigma & v & \nu_\Delta L & M & \end{array} . \tag{10}$$

The N_b bosons, which can be in an s or a d state, must transform symmetrically under $U(6)$, as indicated with the square brackets $[N_b]$. The allowed values for the labels of the subalgebras appearing in the lattice (9) then follow from standard group-theoretical reduction rules [17]. The quantum numbers for $SU_-(3)$ and $SU_+(3)$ are not identical but are obtained from each other under the interchange $\lambda \leftrightarrow \mu$, equivalent to a particle-hole transformation. In the following only the $SU_-(3)$ labels are needed, henceforth denoted for simplicity as (λ, μ) . Note also the presence of the additional labels K and ν_Δ , which are needed to distinguish repeated angular momenta L in a single $SO(5)$ or $SU(3)$ representation.

The preceding discussion defines the concept of a dynamical symmetry, which has received particular attention in the context of the IBM [34]. However, even a simplified IBM-1 Hamiltonian reserves many further surprises when it comes to symmetries, as will be shown in Sections 3 and 4.

2.4 Graphical illustration

The property of dynamical symmetry can be displayed in a graphical fashion. To explain the procedure, consider the IBM-1 Hamiltonian, not in its full complexity of Eq. (2), but a simplified version of it, known as the Hamiltonian of the extended consistent- Q formalism (ECQF) [35, 36], which reads

$$\hat{H}_{ECQF} = \omega \left[(1 - \xi) \hat{n}_d - \frac{\xi}{4N_b} \hat{Q}^x \cdot \hat{Q}^x \right], \quad (11)$$

where \hat{n}_d is an operator that counts the number of d bosons and \hat{Q}_μ^x is the quadrupole operator of the model containing a parameter χ ,

$$Q_\mu^x = [s^\dagger \tilde{d} + d^\dagger s]_\mu^{(2)} + \chi [d^\dagger \tilde{d}]_\mu^{(2)}. \quad (12)$$

The eigenfunctions of the ECQF Hamiltonian do not depend on the overall scale ω but only on ξ and χ , which are therefore the structural parameters of the problem. The parameter ξ ranges from 0, where \hat{H}_{ECQF} reduces to \hat{n}_d , the linear Casimir operator of $U(5)$, to 1, where it reduces to the quadrupole term $\hat{Q}^x \cdot \hat{Q}^x$. The latter is a combination of quadratic Casimir operators of $SU_\pm(3)$ and $SO(3)$ for $\chi = \pm\sqrt{7}/2$ while for $\chi = 0$ it is (up to a constant) the quadratic Casimir operator of $SO(6)$. A convenient range of the parameters is therefore $0 \leq \xi \leq 1$ and $-\sqrt{7}/2 \leq \chi \leq +\sqrt{7}/2$, which allows to attain the $U(5)$, $SU_\pm(3)$, and $SO(6)$ dynamical symmetries. The parameter space of the ECQF Hamiltonian can be represented on a so-called Casten triangle [37], with each point corresponding to a given (ξ, χ) .

The symmetry properties of a given Hamiltonian can be probed with use of a property called “wave-function entropy” [38]. For any eigenstate $|k\rangle$ of the Hamiltonian

that can be expanded in a basis $\{|i\rangle, i = 1, \dots, D\}$ with components α_i^k ,

$$|k\rangle = \sum_{i=1}^D \alpha_i^k |i\rangle, \quad (13)$$

the wave-function entropy is defined as

$$-\sum_{i=1}^D (\alpha_i^k)^2 \ln(\alpha_i^k)^2. \quad (14)$$

The wave-function entropy of a set \mathcal{S} of eigenstates of the Hamiltonian is defined as the sum

$$-\frac{1}{|\mathcal{S}|} \sum_{k \in \mathcal{S}} \left(\sum_{i=1}^D (\alpha_i^k)^2 \ln(\alpha_i^k)^2 \right), \quad (15)$$

where $|\mathcal{S}|$ is the cardinality of the set \mathcal{S} , that is, the number of eigenstates considered in the set, such that the quantity (15) represents the average wave-function entropy per eigenstate. It is clear from the definition that wave-function entropy depends on the basis $|i\rangle$, which in the IBM-1 can be taken as $U(5)$, $SU_\pm(3)$, or $SO(6)$. The property of interest here is that a vanishing wave-function entropy (15) implies a dynamical symmetry. For example, all eigenstates $|k\rangle$ of an $SO(6)$ Hamiltonian have vanishing wave-function entropy in the $SO(6)$ basis: for each eigenstate one component α_i^k equals 1 and all others are 0. However, the same $SO(6)$ Hamiltonian has a non-zero wave-function entropy in the $U(5)$ or $SU_\pm(3)$ basis, where the $SO(6)$ eigenstates have a fragmented structure. The extent of this fragmentation is measured by the wave-function entropy — the higher it is, the more fragmentation occurs. The maximal value of the wave-function entropy is obtained if, in a given basis of dimension D , the eigenstate is completely fragmented with equal components $\pm D^{-1/2}$. The wave-function entropy in that case reaches the value of $\ln D$.

Figure 1 shows the wave-function entropy, on a scale from 0 to its maximum value $\ln D$, in the three different bases $U(5)$, $SU_-(3)$, and $SO(6)$ for all eigenstates of the ECQF Hamiltonian (11) with angular momentum $L = 0$ and boson number $N_b = 15$. As argued above, wave-function entropy can be considered as a measure of dynamical symmetry and vanishes when all quantum numbers of the basis are conserved for all eigenstates. Therefore, a blue region (low wave-function entropy) is found around the vertex that corresponds to the basis used to compute the wave-function entropy. It is seen that the wave-function entropy in the bases $U(5)$ and $SO(6)$ is reflection symmetric with respect to the axis $U(5)$ – $SO(6)$. Following a similar line of argument, it is not necessary to show the wave-function entropy in the $SU_+(3)$ basis since the resulting plot is the reflection-symmetric version of the one obtained in the $SU_-(3)$ basis.

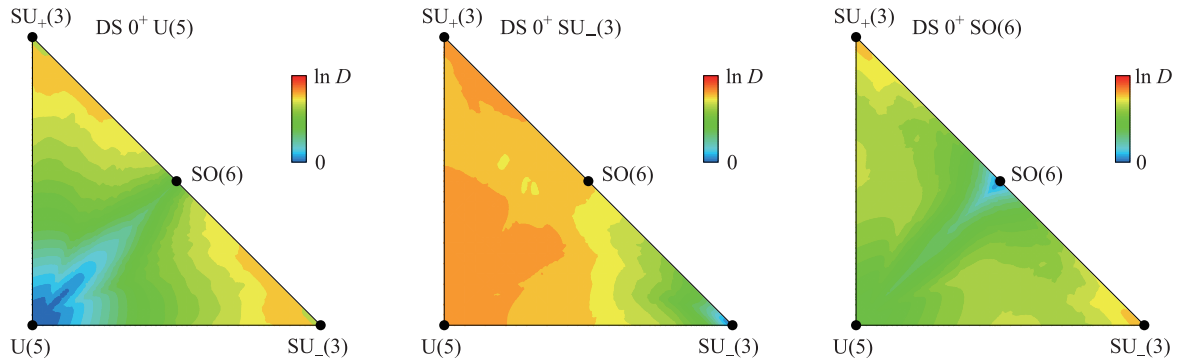


Fig. 1 Illustration of the three dynamical symmetries of the IBM-1. The plots show the wave-function entropy for the ECQF Hamiltonian (11), in the three different bases U(5), SU₋(3), and SO(6) (left, middle, and right), averaged over all eigenstates with angular momentum $L = 0$ and boson number $N_b = 15$.

The preceding results can be conveniently summarized in a single Fig. 2, which shows the lowest value of the wave-function entropy, as calculated in one of the four possible bases, U(5), SU₋(3), SU₊(3), or SO(6). This corresponds to overlaying the three plots of Fig. 1 and taking the minimum value at each (ξ, χ) point, with the added requirement that also the reflection-symmetric version of the middle plot in Fig. 1 is considered to account for the wave-function entropy in the SU₊(3) basis. In the appreciation of Fig. 1 it should be remembered that $\ln D$ (red) is the theoretical maximum of the wave-function entropy and that green corresponds to about half that maximum, that is, still considerable mixing. Only deep-blue areas in the triangle of Fig. 2 indicate closeness to a dynamical symmetry and, since not much blue is seen and green areas dominate, one is tempted to conclude that most points of the triangle — and therefore most ECQF Hamiltonians — are not amenable to any symmetry treatment. The main purpose of this contribution is to show that this conclusion would be wrong.

3 Partial dynamical symmetries

The results of Fig. 2 are obtained with the expression (15) where the set \mathcal{S} is defined as the eigenstates with angular momentum $L = 0$ and boson number $N_b = 15$. Similar results are obtained if the sum is taken over *all* eigenstates but for different choices of L and N_b . However, one is usually interested only in eigenstates at low energy and it makes therefore sense to restrict the set \mathcal{S} to such states. In addition, it may be that *some* quantum numbers of a dynamical-symmetry classification are broken while others are conserved. Symmetry characteristics of this kind can be studied by restricting the sum in Eq. (15) to a subset of eigenstates of the Hamiltonian and/or by decomposing the eigenstates onto

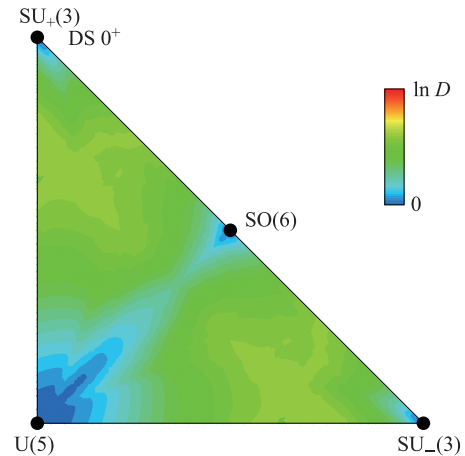


Fig. 2 Where in the IBM-1 does a dynamical symmetry occur? The plot shows the lowest value of the wave-function entropy, as calculated in one of the four possible bases, U(5), SU₋(3), SU₊(3), or SO(6), for all eigenstates of the ECQF Hamiltonian (11) with angular momentum $L = 0$ and boson number $N_b = 15$.

subspaces characterized by a single label (instead of all labels of a dynamical-symmetry chain). Such restricted symmetries are known collectively as partial dynamical symmetries, of which there are three different types. In the first, PDS-1 [39, 40], only eigenstates in a restricted set \mathcal{S} retain all quantum numbers. In the second type, PDS-2 [41, 42], all eigenstates of the IBM-1 Hamiltonian conserve a single label of one of the classifications (10). To render the definition of the associated wave-function entropy more explicit in this case, one decomposes each eigenstate onto subspaces spanned by the representations of single subalgebra G of U(6), leading to the expansion

$$|k\rangle = \sum_{j=1}^d \sum_m \alpha_{jm}^k |jm\rangle, \tag{16}$$

where the first sum runs over the d different representations of G while the second enumerates the basis states that span this representation. With the definition of the coefficients

$$(\beta_j^k)^2 = \sum_m (\alpha_{jm}^k)^2, \quad (17)$$

the relevant wave-function entropy of a set \mathcal{S} of eigenstates can be written as

$$-\frac{1}{|\mathcal{S}|} \sum_{k \in \mathcal{S}} \left(\sum_{j=1}^d (\beta_j^k)^2 \ln(\beta_j^k)^2 \right), \quad (18)$$

which, by a similar argument as above, has a maximum value of $\ln d$. Finally, the third type of partial dynamical symmetry, PDS-3 [43], combines the two properties and thus concerns a subset of eigenstates, which is analyzed with respect to a single label.

Algorithms exist for the construction of Hamiltonians with the required symmetry properties, PDS- i , and can be found in the review [44].

As before, the concept of partial dynamical symmetry can be illustrated graphically with the wave-function entropy of the ECQF Hamiltonian (11). Figures 3 to 5 shows the results of nine different calculations, varying the set \mathcal{S} of eigenstates, the choice of the label [n_d , (λ, μ) , or σ], and the basis [U(5), SU $_-$ (3), or SO(6)], always for angular momentum $L = 0$ and boson number $N_b = 15$. On the left-hand panel of each figure is plotted the wave-function entropy of the 0_1^+ eigenstate, that is, for $\mathcal{S} = \{0_1^+\}$, decomposed in the three different bases, U(5), SU $_-$ (3), or SO(6), in Figs. 3, 4, and 5, respectively. In the middle panel the wave-function entropy is summed over all 0^+ eigenstates but the components β_j^k correspond to the decomposition onto subspaces that are characterized by a single label, n_d , (λ, μ) , or σ , as in Eq. (18). The wave-function entropy of the 0_1^+ ground state with respect to a single label is shown on the right-hand panel of Figs. 3 to 5. The figures therefore illustrate graphically the three types of partial dynamical symmetry PDS- i . A remarkable result is found as regards the conservation of the SO(6) label σ namely, the existence of an entire band of ECQF Hamiltonians with close to

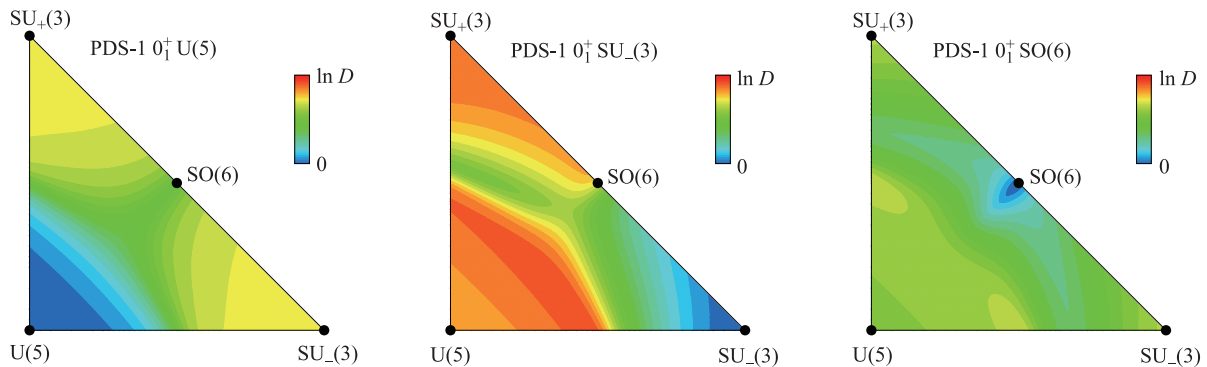


Fig. 3 Illustration of the three partial dynamical symmetries of the type PDS-1 in the IBM-1. The plots show the wave-function entropy of the 0_1^+ eigenstate with respect to all labels of the U(5), SU $_-$ (3), and SO(6) limits for the ECQF Hamiltonian (11) with boson number $N_b = 15$.

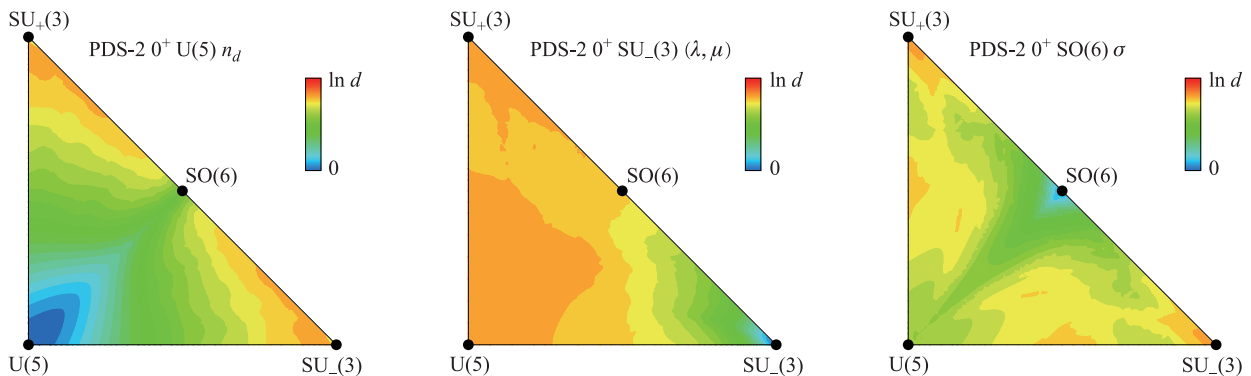


Fig. 4 Illustration of the three partial dynamical symmetries of the type PDS-2 in the IBM-1. The plots show the average wave-function entropy of all 0^+ eigenstates with respect to a single label (as indicated) of the U(5), SU $_-$ (3), and SO(6) limits for the ECQF Hamiltonian (11) with boson number $N_b = 15$.

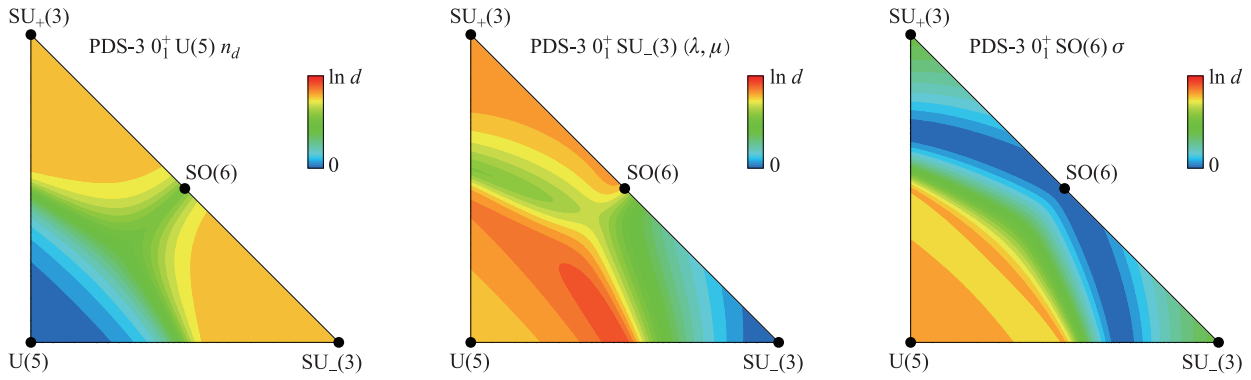
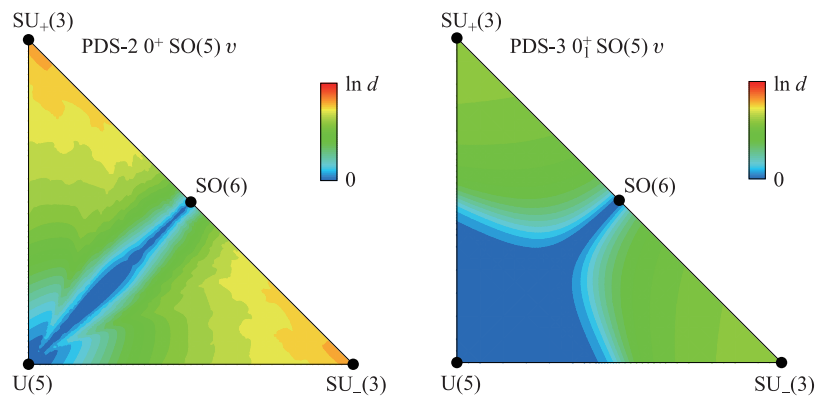


Fig. 5 Illustration of the three partial dynamical symmetries of the type PDS-3 in the IBM-1. The plots show the wave-function entropy of the 0_1^+ eigenstate with respect to a single label (as indicated) of the $U(5)$, $SU_-(3)$, and $SO(6)$ limits for the ECQF Hamiltonian (11) with boson number $N_b = 15$.

Fig. 6 Illustration of the $SO(5)$ partial dynamical symmetry in the IBM-1. The plots show the wave-function entropy for the eigenstates of the ECQF Hamiltonian (11) with angular momentum $L = 0$ and boson number $N_b = 15$. Left: Average wave-function entropy of all 0^+ eigenstates with respect to the $SO(5)$ label v (PDS-2). Right: Wave-function entropy of the 0_1^+ eigenstate with respect to v (PDS-3).



exact $SO(6)$ symmetry in the ground state [45], see the left-hand panel of Fig. 5.

A partial dynamical symmetry can also be defined with respect to the $SO(5)$ label v — associated with d -boson seniority. Given its single-label character, it concerns either PDS-2 or PDS-3. The left panel in Fig. 6 shows that the conservation of the $SO(5)$ label is exact for the entire $U(5)$ – $SO(6)$ transitional Hamiltonian, as is known since long [41]. Moreover and more generally, it can be shown that the $U(5)$ – $SO(6)$ transitional Hamiltonian is integrable [46]. The right panel in Fig. 6 illustrates the conservation of the $SO(5)$ label in the 0_1^+ eigenstate and it is seen that a large area corresponds to ECQF Hamiltonians with approximate $SO(5)$ symmetry in the ground state. Selection rules associated with this symmetry can therefore be expected to have a wide validity in nuclei.

These results can be summarized again in a single plot, Fig. 7, which shows the lowest value of the wave-function entropy of the 0^+ ground state, calculated with respect to the $U(5)$, $SU_-(3)$, $SU_+(3)$, $SO(6)$, or $SO(5)$ labels. The figure illustrates that a large fraction of the parameter space of the ECQF Hamiltonian (11) enjoys an ap-

proximate symmetry of one kind or another in its ground state.

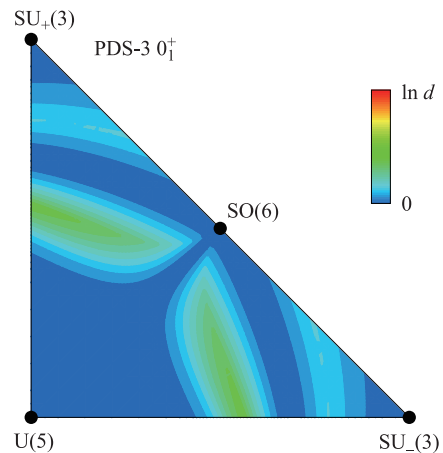


Fig. 7 Where in the IBM-1 does a partial dynamical symmetry occur? The plot shows the lowest value of the wave-function entropy, as calculated with respect to five possible labels n_d , (λ, μ) , (μ, λ) , σ , or v , for the 0_1^+ eigenstate of the ECQF Hamiltonian (11) for boson number $N_b = 15$ (PDS-3).

4 Quasi dynamical symmetries

Quasi dynamical symmetries constitute another extension of the concept of dynamical symmetry. They can be given a mathematical definition in terms of embedded representations [47]. The (admittedly loose) physical interpretation of quasi dynamical symmetries is that observables can be consistent with a certain symmetry, which is in fact broken in the Hamiltonian. Typically, this situation occurs for a Hamiltonian that is transitional between two limits and which retains, for a certain range of its parameters, the characteristic patterns of one of those dynamical symmetries [48–51]. In more mathematical terms a coherent mixing of representations in a subset of eigenstates is at the basis of this “apparent” symmetry.

The validity of a quasi dynamical symmetry must be probed by examining the similarity in the decomposition of certain eigenstates. A quantitative measure of quasi dynamical symmetry can be introduced by rewriting the expansion (13) in yet another way,

$$|k\rangle \equiv |rL\rangle = \sum_{i=1}^{D_L} \alpha_i^{rL} |i\rangle, \quad (19)$$

where $\{k\} \equiv \{rL\}$, that is, r contains all labels except the angular momentum L . The measure of quasi dynamical symmetry is defined as $\Omega_r \equiv \sqrt{1 - \Theta_r}$ where Θ_r is the average over pairs $L \neq L'$ of the quantities

$$\Theta_r^{LL'} \equiv \sum_{i=1}^{D_L} \alpha_i^{rL} \alpha_i^{rL'}. \quad (20)$$

A vanishing Ω_r therefore indicates a perfect correlation between the expansion coefficients α_i^{rL} with different angular momenta L . In a typical application of quasi dynamical symmetry one wishes to probe the similarity of

the structure of yrast states, which implies the identification of r with the labels of the ground-state band, that is, for $n_d = L/2$ in $U(5)$, $(\lambda, \mu) = (2N, 0)$ in $SU_-(3)$, and $\sigma = N$ in $SO(6)$. Figure 8 shows the quantity Ω_r for the ECQF Hamiltonian (11) in the three different bases $U(5)$, $SU_-(3)$, and $SO(6)$, for the angular momenta $L = 0, 2, \dots, 10$ and boson number $N_b = 15$.

It is obvious that connections exist between the concepts of partial and dynamical symmetry. For example, the band structure in the wave-function entropy of the ground state with respect to σ in Fig. 5 also shows up in the $SO(6)$ quasi dynamical symmetry of Fig. 8. A remarkable finding of this analysis is that the partial conservation of one symmetry may occur simultaneously with the coherent mixing of another, incompatible symmetry.

Again one can summarize these findings in a single Fig. 9, which displays the minimum value of the measure Ω_r in any of the four bases, $U(5)$, $SU_-(3)$, $SU_+(3)$, or $SO(6)$. Large areas of the parameter space are seen to be blue, that is, to display a quasi dynamical symmetry.

The contrast between the results shown for dynamical symmetries on the one hand, Fig. 2, and those for partial and quasi dynamical symmetries on the other, Figs. 7 and 9, is startling. Dynamical symmetries are restricted to small regions in the parameter space (the blue areas in Fig. 2) and therefore are expected to have only restricted applicability in nuclei. This is not the case for the extended concepts of partial and quasi dynamical symmetries, as illustrated in Figs. 7 and 9, where large bands of blue are found in the triangle.

5 Concluding remarks

Dynamical symmetries are scarce while partial dynamical symmetries and quasi dynamical symmetries are ubiquitous. This has been the main theme of this con-

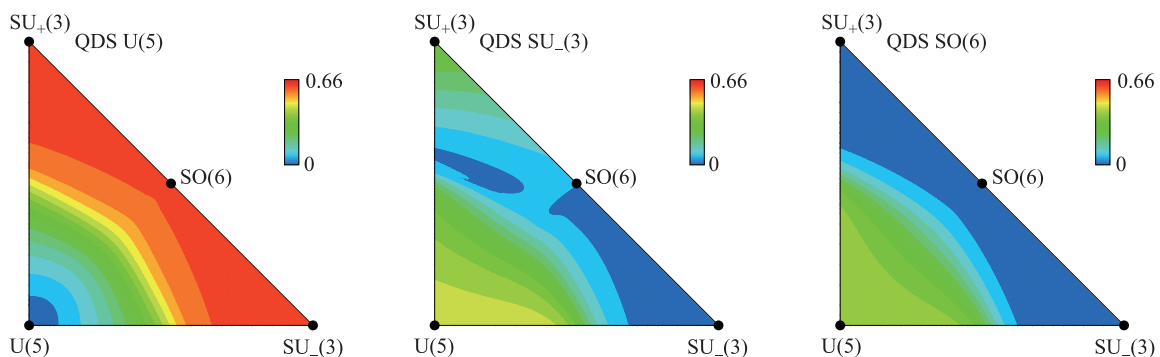


Fig. 8 Illustration of the three quasi dynamical symmetries of the IBM-1. The plots show the quantity Ω_r , a measure of quasi dynamical symmetry as defined in the text, for the ECQF Hamiltonian (11) in the three different bases $U(5)$, $SU_-(3)$, and $SO(6)$ (left, middle, and right), for yrast eigenstates with angular momenta $L = 0, 2, \dots, 10$ and for boson number $N_b = 15$.

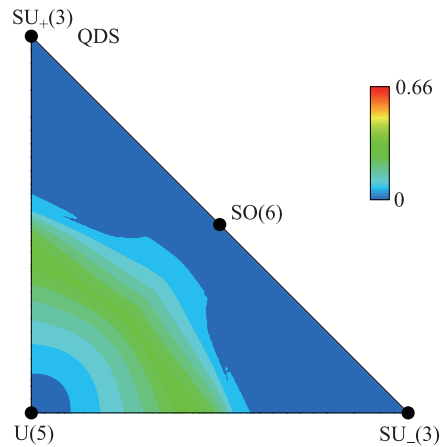


Fig. 9 Where in the IBM-1 does a quasi dynamical symmetry occur? The plot shows the lowest value of Ω_r in any of the four bases $U(5)$, $SU_-(3)$, $SU_+(3)$, and $SO(6)$, for yrast eigenstates of the ECQF Hamiltonian (11) with angular momenta $L = 0, 2, \dots, 10$ and for boson number $N_b = 15$. The quantity Ω_r is a measure of quasi dynamical symmetry, as defined in the text.

tribution. It has been examined in the context of the interacting boson model for the schematic Hamiltonian of the extended consistent- Q formalism and illustrated by a graphical representation of wave-function entropy in various bases. In no way do these results represent the complete symmetry analysis of the IBM. A general Hamiltonian of the interacting boson model with up to two-body interactions allows the occurrence of exact dynamical symmetries of various partialities, some of which are not or only approximately present in the schematic Hamiltonian of the extended consistent- Q formalism. Also, given the composite nature of the bosons three-body interactions between them are to be expected, further enriching the symmetry features of the model. It is remarkable that more than forty years after the proposal by Arima and Iachello, the full symmetry content of the interacting boson model still remains to be uncovered.

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