

Hu-sheng WU, Jun-jie XUE, Ren-bin XIAO, Jin-qiang HU, 2020. Uncertain bilevel knapsack problem based on an improved binary wolf pack algorithm. *Frontiers of Information Technology & Electronic Engineering*, 21(9):1356-1368. <https://doi.org/10.1631/FITEE.1900437>

Uncertain bilevel knapsack problem based on an improved binary wolf pack algorithm

Key words: Bilevel knapsack problem; Uncertainty; Improved binary wolf pack algorithm

Corresponding author: Ren-bin XIAO

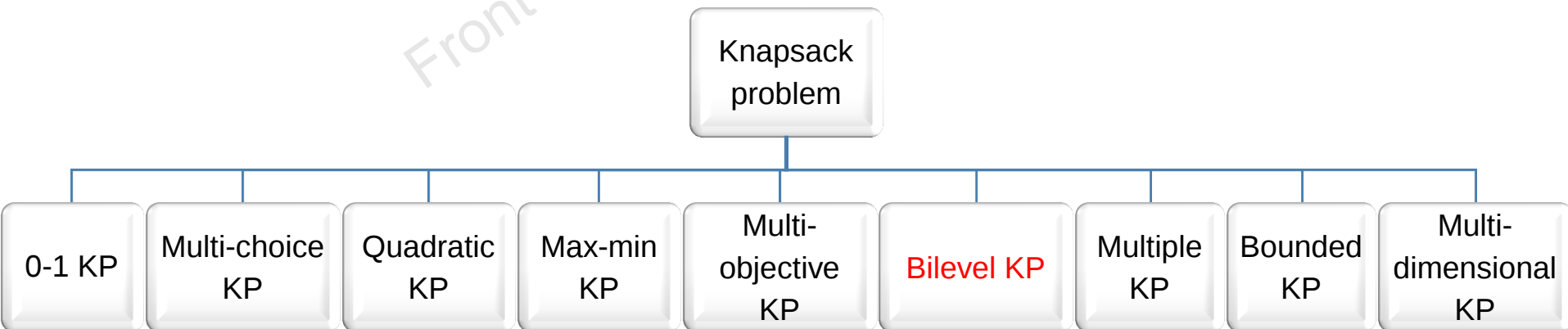
E-mail: rbxiao@hust.edu.cn

 ORCID: <https://orcid.org/0000-0003-0951-2734>

Knapsack problem

- Knapsack problem (KP) is a well-known combinatorial optimization problem with wide applications and various types.

Domain	Application
Industry	Material distribution
Economy	Capital budget
Finance	Investment decision
Logistics	Cargo loading optimization
Computer	Distributed system
Information security	Construction of public key cryptosystem



Motivation

- ❑ Bilevel KP (BKP) parameters are often **indeterminate**, particularly for issues related to combat, such as an armament transportation problem.
- ❑ Many researchers solve the uncertain BKP (UBKP) using **probability theory**, while the effective probability distributions of many real-world problems cannot be obtained due to lack of sufficient sample data.
- ❑ **Fuzzy theory** cannot effectively deal with the indeterministic reliability, and the related fuzzy KP also has certain limitations.

UBKP model

- ❑ To handle UBKPs, an uncertain solution can be found by applying the $\mathcal{P}_E$ Nash equilibrium and $\mathcal{P}_E$ Stackelberg–Nash equilibrium to **transform UBKP** to a **corresponding equivalent deterministic model**.
- ❑ BKP involves **two decision-makers** interacting hierarchically. A leader (responsible for a subset of variables) must explicitly consider the reaction of a follower (responsible for another subset of variables) in its optimization process.

Improved binary wolf pack algorithm

- ❑ The evolutionary improved binary wolf pack algorithm (IBWPA) is a swarm intelligence based optimization algorithm, comprising **one regulation**, **two operators**, and **three intelligent behaviors**.

Swarm intelligence



Wolf pack algorithm



Leader wolf



Scout wolf



Ferocious wolf



Cooperative hunting

Scouting behavior

Intelligent hunting behavior

Upgrading

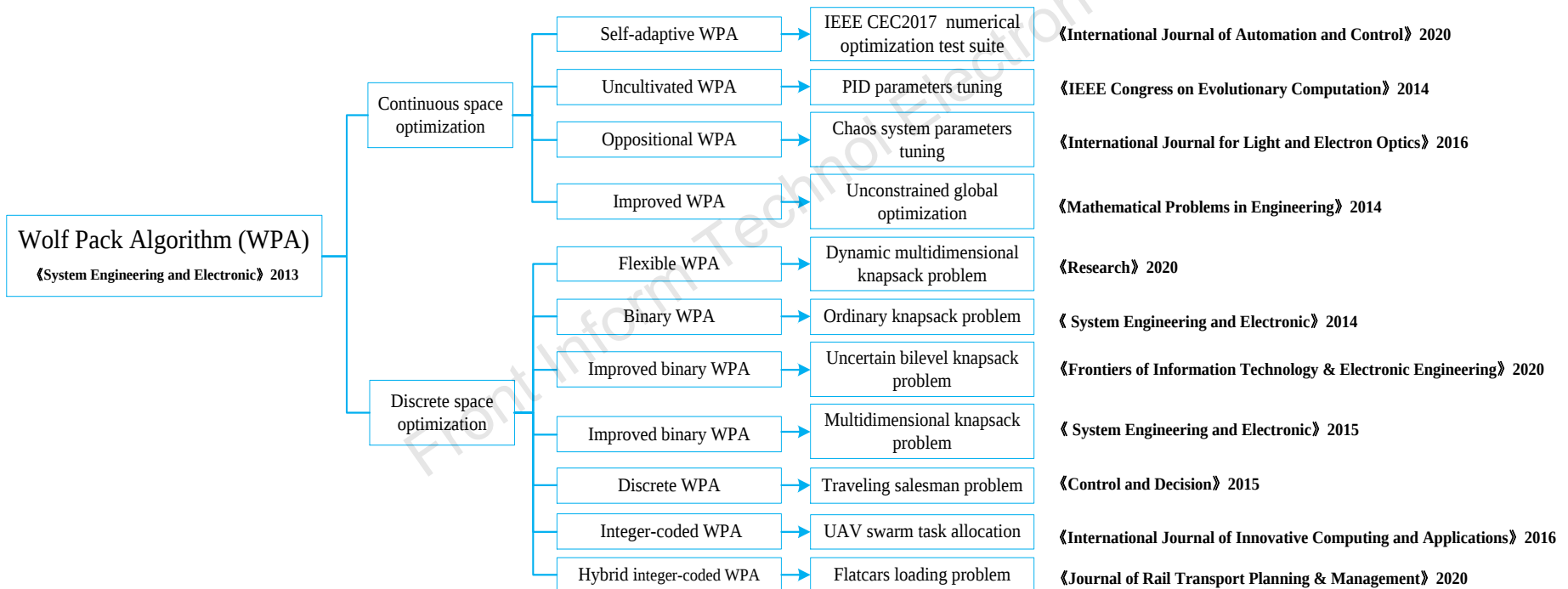
Wolf leader regulation

Invert operator

Move operator

Applications of IBWPA

- ❑ Wolf pack algorithm (WPA) has been applied in many real-world problems and a series of derivative versions have been developed.



Move operator

- Move operator preserves the same part of items between the wolf leader and the artificial wolf to retain the **elite advantages** and to increase **population diversity**.

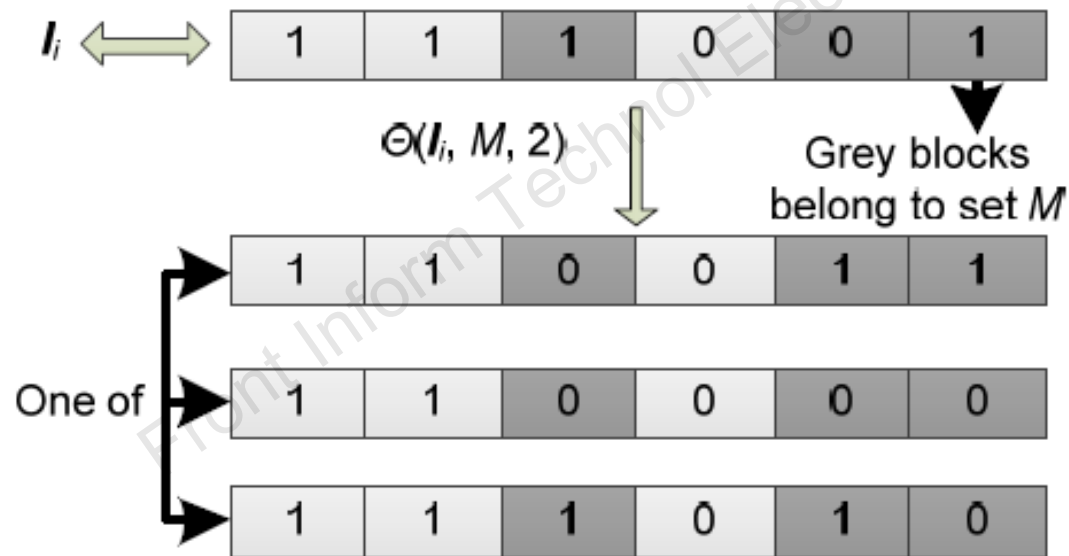


Fig. 1 Illustration of the move operator

Simulations

- ❑ To demonstrate the effectiveness of IBWPA in solving UBKP, simulations on classic KP benchmarks were performed because UBKP is a special type of KP.

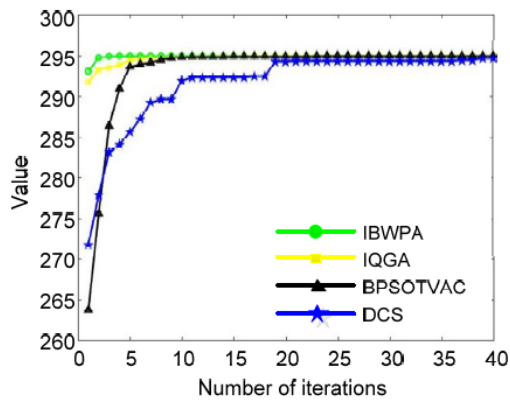


Fig. 3 Average convergence curves for KP1

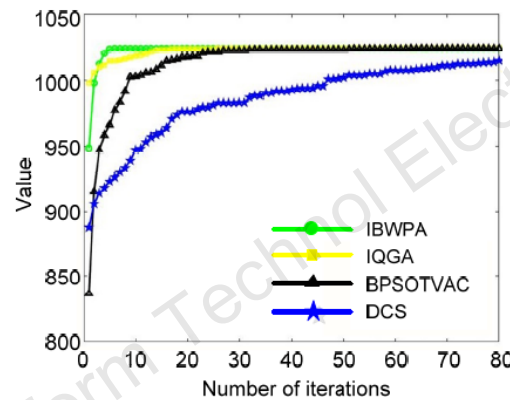


Fig. 4 Average convergence curves for KP2

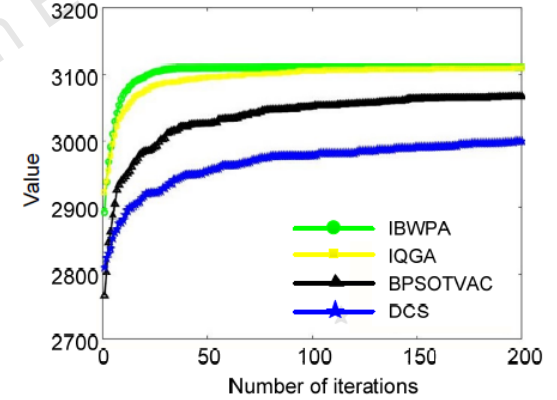


Fig. 5 Average convergence curves for KP3

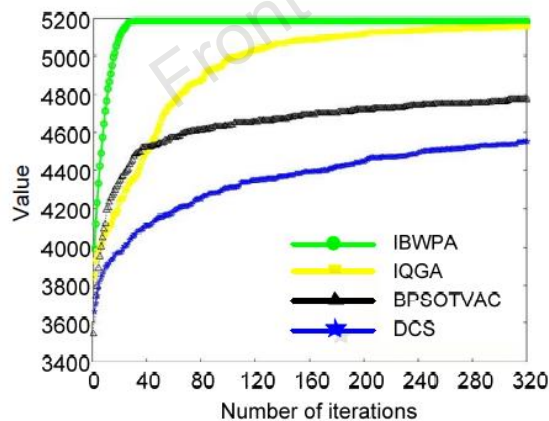


Fig. 6 Average convergence curves for KP4

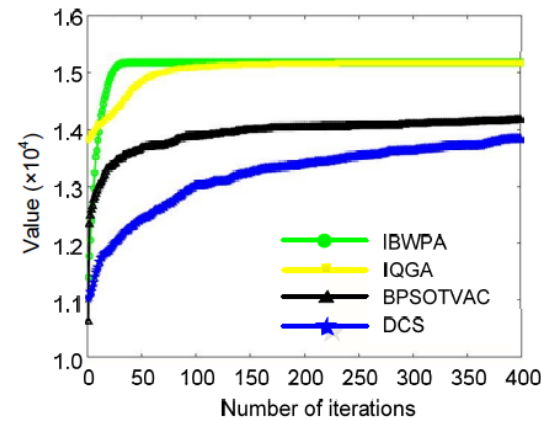


Fig. 7 Average convergence curves for KP5

Applications

- An **armament transportation example** with uncertain parameters is applied as a case study. Several armaments and combat groups must be transported by airplane. The frontier commander must maximize the combat capacity in the frontier, and the transportation commander attempts to guarantee safety in the transportation process.

Conclusions

- ❑ A **UBKP model** which is a special type of BKP with uncertain variables is proposed.
- ❑ An **uncertain solution** has been developed to transform UBKP to an equivalent deterministic model.
- ❑ Computational efficiency has been improved by the proposed **evolutionary IBWPA**.
- ❑ The performance of IBWPA was **much better** than that of the algorithms compared for several typical knapsack problem benchmark tests.
- ❑ IBWPA has been applied to an **armament transportation problem** under uncertain parameters.



Hu-sheng WU received the BS degree in Automobile Command, the ME degree in Military Equipment Science from Armed Police Force Engineering University in 2008 and 2011, respectively, and the PhD degree in Systems Engineering from the Air Force Engineering University, Xi'an, China in 2014. He is currently an Associate Professor with the School of Equipment Management and Support in Armed Police Force Engineering University. His research interests include swarm intelligence, unmanned system and its combat operation, and military intelligent equipment.



Ren-bin XIAO received the BS degree in Ship Engineering, the ME degree in Ship Hydrodynamics, and the PhD degree in Systems Engineering from Huazhong University of Science and Technology (HUST), in 1986, 1989, and 1993, respectively. He is currently a Professor with the School of Artificial Intelligence and Automation, HUST. His research interests include swarm intelligence, social computing, and innovative design of complex products.