

Jin Wang, Feng Shu, Ri-qing Chen, Yu-di Cui, Yu Chen, Jun Li, 2016. Adaptive robust beamformer for multi-pair two-way relay networks with imperfect channel state information. *Frontiers of Information Technology & Electronic Engineering*, 17(3):265-280.  
<http://dx.doi.org/10.1631/FITEE.1500134>

# Adaptive robust beamformer for multi-pair two-way relay networks with imperfect channel state information

**Key words:** Multi-pair two-way relay, Adaptive robust beamformer, Channel state information (CSI), Maximum signal-to-interference-and-noise ratio (Max-SINR), Maximum signal-to-leakage-and-noise ratio (Max-SLNR)

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# Motivation

- In wideband multi-pair two-way relay networks, the performance of beamforming at a relay station (RS) is intimately related to the accuracy of the channel state information (CSI) available.
- The accuracy of CSI is determined by Doppler spread, delay between beamforming and channel estimation, and density of pilot symbols, including transmit power of pilot symbols.
- Therefore, we develop an adaptive robust Max-SINR plus Max-SLNR beamformer of tracking the channel variation by taking Doppler spread, delay between channel estimation and beamforming, and the density and power of pilot symbols into account.

# Paper contribution

- We design the transmit and receive beamforming matrices at the RS by making use of Max-SINR and Max-SLNR criteria in the presence of imperfect CSI.
- The coefficients of the Gaussian-Markov CSI error model are modeled as a function of CSI delay, Doppler spread, and signal-to-noise ratio, and can be estimated in real time.
- In accordance with the real-time estimated coefficients of the error model, an adaptive robust Max-SINR plus maximum Max-SLNR beamformer at an RS is proposed to track the variation of CSI error.

# System model

- One central relay station (RS) with  $N$  antennas
- $K$  pairs of mobile stations (MSs) with  $M$  antennas

$$\begin{aligned} \mathbf{r}_{k_i}^{uq} = & \beta (\mathbf{G}_{k_i}^{uq})^T \mathbf{W}_{RS}^{uq} \mathbf{H}_{k(-i)}^{uq} \mathbf{s}_{k(-i)}^{uq} \\ & + \beta (\mathbf{G}_{k_i}^{uq})^T \mathbf{W}_{RS}^{uq} \mathbf{H}_{k_i}^{uq} \mathbf{s}_{k_i}^{uq} + \mathbf{c}_{k_i}^{uq} \\ & + \beta (\mathbf{G}_{k_i}^{uq})^T \mathbf{W}_{RS}^{uq} \mathbf{z}_{RS}^{uq} + \mathbf{z}_{k_i}^{uq}, \end{aligned}$$

# CSI error model

$$\widehat{H}_{k_i}^{(u-\Delta u)q} = \rho_H H_{k_i}^{uq} + \sqrt{1 - \rho_H^2} H_{e,k_i}^{uq}$$

$$\widehat{G}_{k_i}^{(u-\Delta u)q} = \rho_G G_{k_i}^{uq} + \sqrt{1 - \rho_G^2} G_{e,k_i}^{uq}$$

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# Proposed adaptive robust beamformer

$$\mathbf{W}_{RS}^{uq} = \sum_{k=1}^K \sum_{i \in \{a,b\}} \mathbf{W}_{t,k_i}^{uq} \left( \mathbf{W}_{r,k(-i)}^{uq} \right)^T$$

Max-SLNR

$$B_{k_i} = \frac{\Psi_1}{\sigma_{RS}^2 \mathbf{I}_N + P_{RS} N^{-1} (\Psi_2 + \Psi_3)}$$

Max-SINR

$$\mathbf{A}_{k(-i)} = \frac{\Phi_1^T}{\sigma_{RS}^2 \mathbf{I}_N + P_{MS} M^{-1} (\Phi_2 + \Phi_3)^T}$$

# Real-time estimation of $\rho$

$$\rho_{H,k_i}^u = \rho_{H,k_i}^{ud} \rho_{H,k_i}^{ue}$$

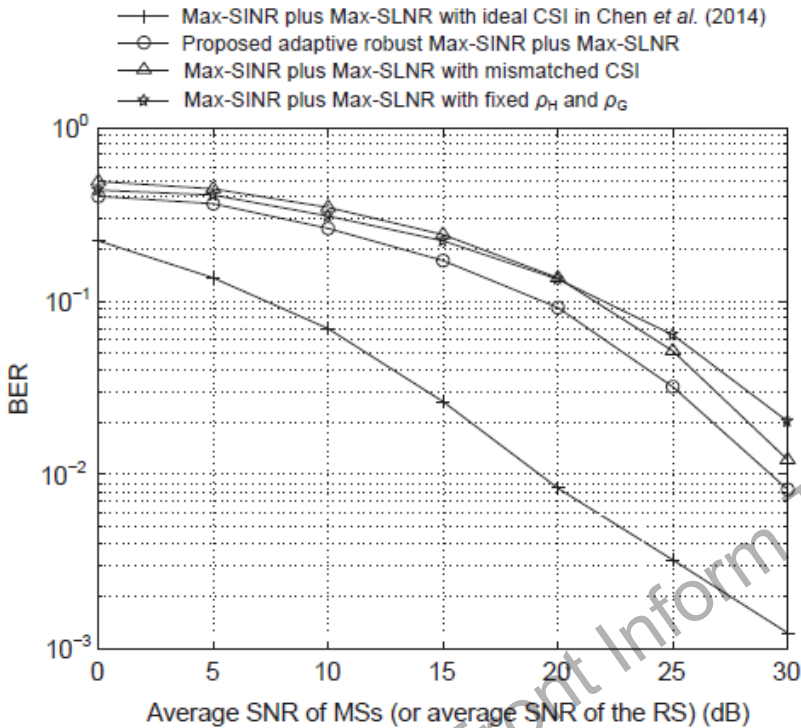
effect of Doppler spread

$$\rho_{H,k_i}^{ud} = \frac{\Re_{HH,k_i}(\Delta u, 0)}{\Re_{HH,k_i}(0, 0)}$$

effect of channel estimation error

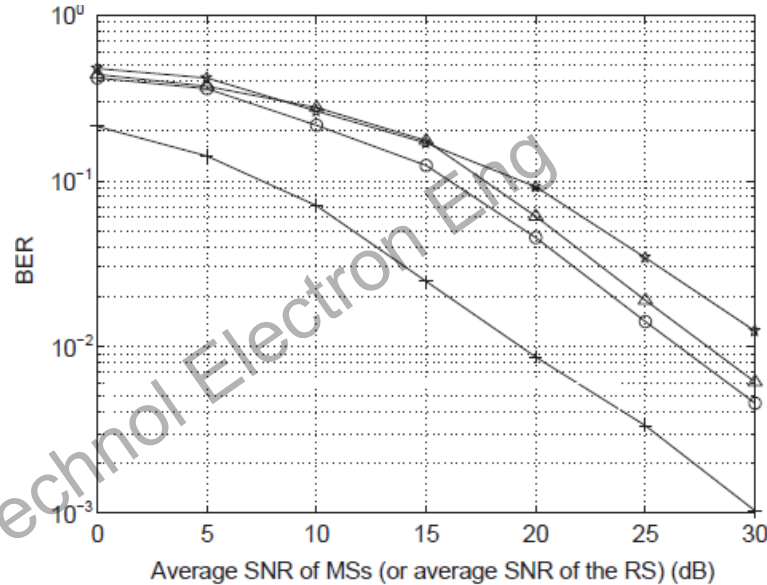
$$\rho_{H,k_i}^{ue} = \frac{\text{SNR}_{H,k_i}^{up}}{1 + \text{SNR}_{H,k_i}^{up}}$$

# Major results

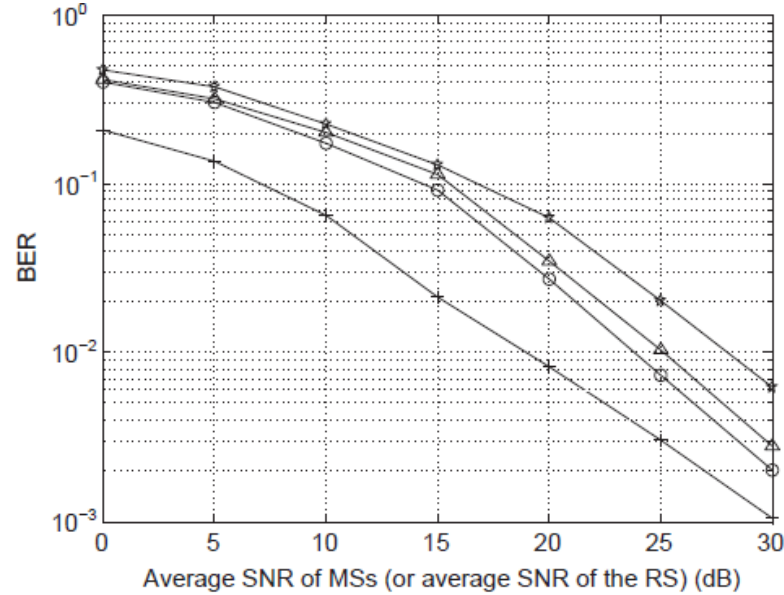


$\alpha=0.5$

Curves of BER versus SNR of the proposed adaptive robust beamformer and existing non-adaptive ones ( $\Delta m f_d T_s = 0.01$ )

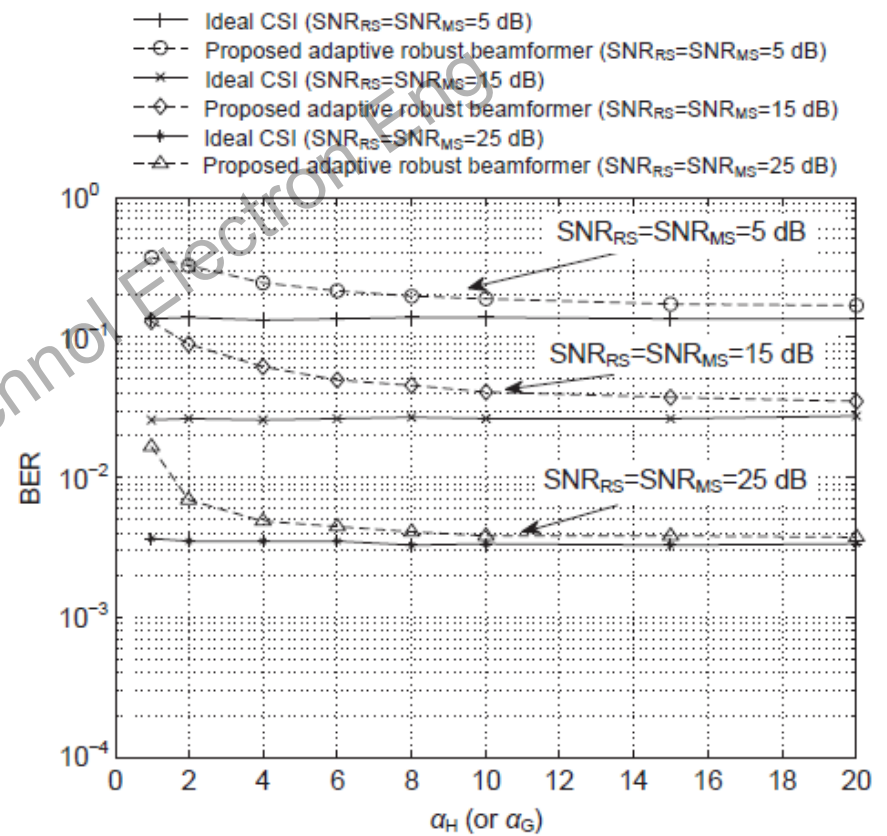
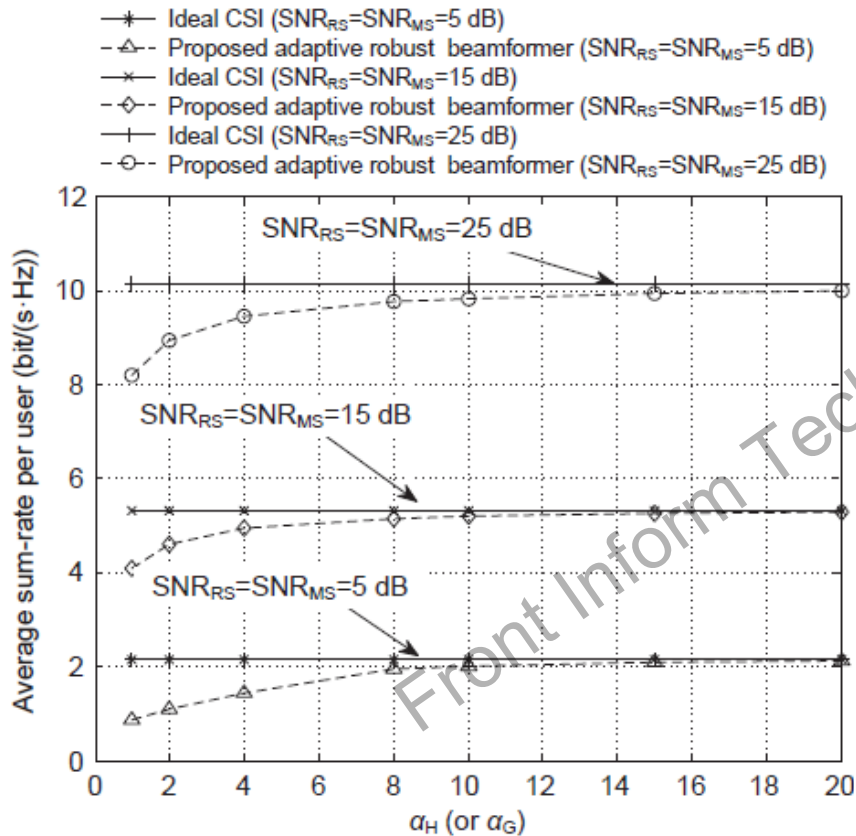


$\alpha=1.0$



$\alpha=2.0$

# Major results (Con'd)



Curves of sum-rate and BER versus  $\alpha$  of the proposed adaptive robust beamformer at  $\text{SNR}_{\text{RS}}=\text{SNR}_{\text{MS}}=5$  dB, 15 dB, 25 dB ( $\Delta m f_d T_s = 0.01$ )

# Conclusions

- By real-time estimation of Doppler spread and SNR in the channel, an adaptive robust Max-SINR plus Max-SLNR beamformer at an RS is proposed to take into account some uncertainty or possible variation in the channel matrix.
- From simulation results and analysis, we find that the proposed robust method can adaptively track channel variation and performs much better than existing robust and non-robust Max-SINR plus Max-SLNR non-adaptive schemes.