

Appendixes

Theorem 1. *Given a node v , if exists a neighbor node v' of v , the tree node $X(v')$ is a passing node on the path from root node r to v in the graph-decomposed tree Λ rooted by node r .*

Proof [For Theorem 1] Considering a node v and its neighbor nodes $N(v)$, node v can be abstracted as a tree node $X(v)$, satisfying $N(v) = X(v)-v$. If exists a tree node $X(v')$, satisfying that $X(v')$ is a parent of $X(v)$, then $v' \in X(v)-v$. v' is connected with all other neighbor nodes $X(v)-v-v'$ after v is deleted. Thus, if exists a tree node $X(v'')$, satisfying that $X(v'')$ is a parent of $X(v')$, such that $X(v'') \in (X(v)-v-v') \cup (X(v')-v')$. Similarly, all tree nodes abstracted from neighbor nodes of v can be found into a path from root node to v .

Lemma 1. *Given a query node q and a data node v , if exists a minimum common ancestor v' of q and v , the shortest path $dist(q, v)$ is equal to the sum of shortest paths $dist(q, v')$ and $dist(v', v)$.*

Proof [For Lemma 1] If there exists one other node v'' , satisfying the shortest path $dist(q, v)$ is equal to the sum of shortest paths $dist(q, v'')$ and $dist(v'', v)$, then there must exist one or more across-path edges to connect the node v'' . However, it is impossible to exist one across-path edge in graph-decomposed tree according to Theorem 1, because any node v and its neighbor nodes only be found into the path from root node r to v .