

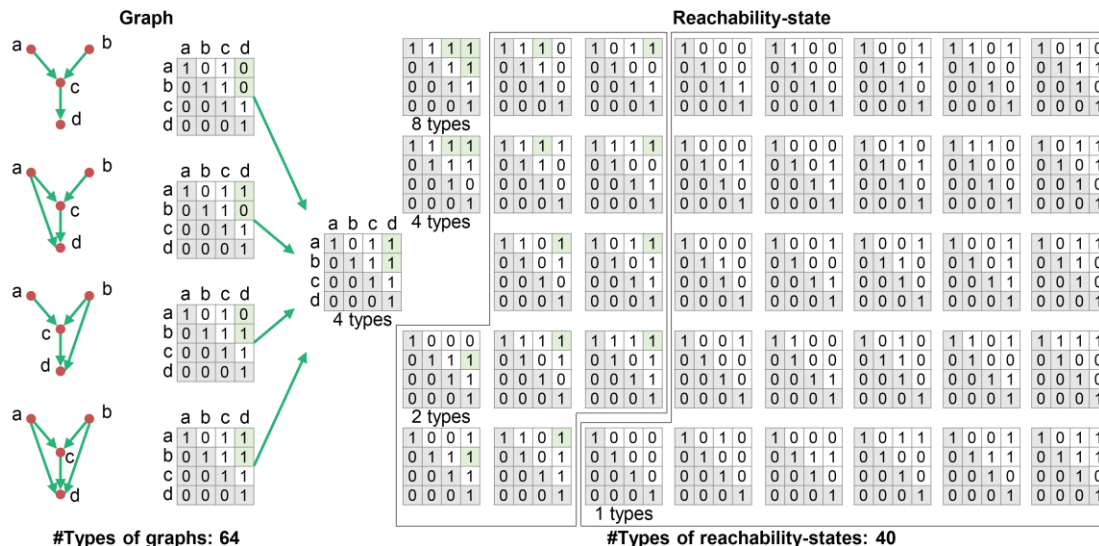
Reachability-state Encoding: Bridging tradeoffs between the Minimal Storage and the Fastest Query for Reachability Query

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Frontiers of Computer Science, DOI: [10.1007/s11704-025-50122-8](https://doi.org/10.1007/s11704-025-50122-8)

Problems & Ideas

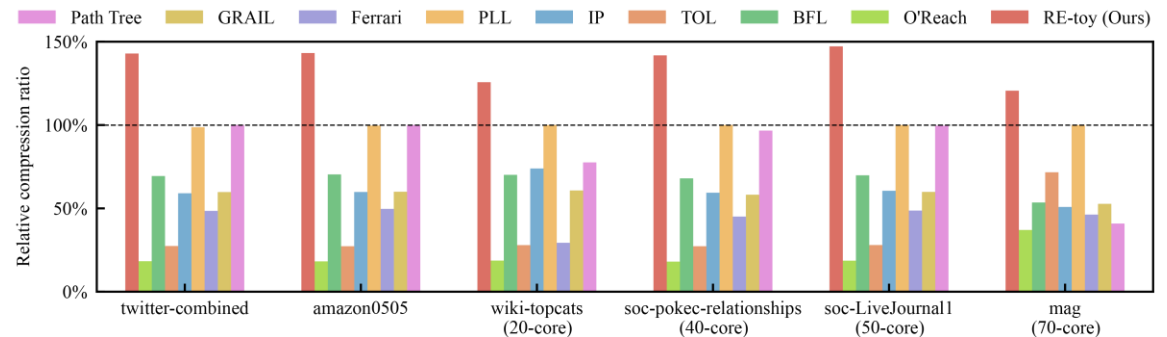
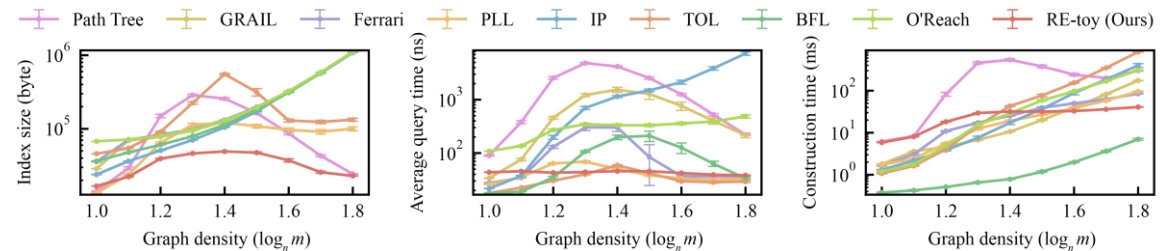
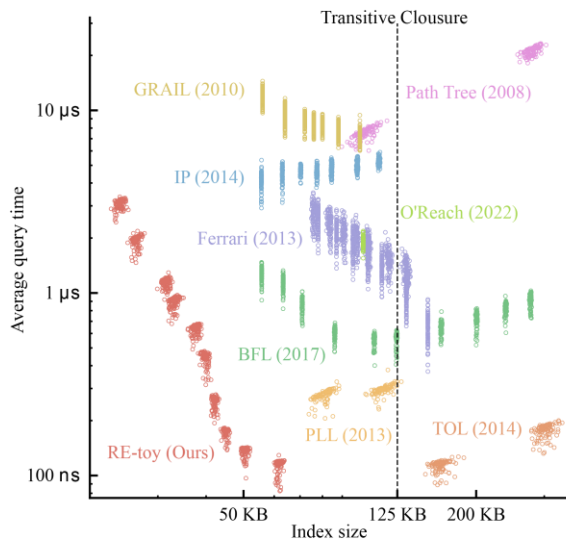
- Problems of conventional reachability query methods :
 - Traditional algorithms like DFS and transitive closure suffer from either slow query time or large storage overhead.
 - Existing indexing techniques often fix the tradeoff point, lacking flexible control over the balance between space and query efficiency.
- Ideas: Reachability-state Encoding (RE) rethinks graph indexing by compressing the transitive closure into a compact, entropy-guided format, enabling fine-grained control over storage-query tradeoffs.



Reachability-states on 4-node directed acyclic graphs. The 0/1 in the matrix of the graph indicates the existence of an edge, and 0/1 in the matrix of reachability-state indicates the existence of a path. The values in green cells do not affect the reachability-state of the graph, so a reachability-state may correspond to multiple types of graph adjacency matrices.

Main Contributions

- Contributions:
 - Propose the Reachability-state Encoding (RE) framework enabling smooth tradeoffs between space and time
 - Introduce reachability-state entropy to quantify the compressibility of reachability information
 - Develop the RE-toy prototype, demonstrating superior performance across diverse datasets



Efficiency and Robustness of RE-toy. Left: RE-toy achieves flexible tradeoffs between index size and query time, consistently approaching the optimal boundary. Right up: RE-toy maintains stable performance across varying graph densities, with low growth in space and time costs. Right down: On real-world datasets, RE-toy achieves over 30% average improvement in index size compared to the best existing algorithms.