

# A Program Logic for Obstruction- freedom

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# Problems & Ideas

- Reasoning about and verifying obstruction-freedom is a big challenge
  - Obstruction-free implementations are practical for software transactional memory (STM) and in anonymous and fault-tolerant distributed computing.
  - Existing work can only verify obstruction-freedom of specific data structures.
  - Following traditional idea (i.e., treat obstruction-freedom as a liveness property and verify it by proving “something good will eventually happen”) encounters thorny problems.
- Our idea: verify obstruction-freedom by proving “some bad thing never happens”
  - Inspired by the method of verifying safety properties.
  - The bad things should be prevented:  
*divergences caused by finite interference.*
  - The implementation in the right figure is not obstruction-free because the “bad thing” occurs.

```
f() {  
1 i:=0;  
2 while (i=1) skip;  
3 return  
}  
g() {  
4 i:=i+1;  
5 return  
}  
client:  
6 f() || g()
```

# Main Contributions

- A program logic that can formally verify obstruction-freedom

$$\frac{R \vdash \{p \wedge B\} C \{p\}}{R \vdash \{p\} \text{while}(B)\{C\} \{p \wedge \neg B\}} \quad (\text{Standard WHILE rule})$$



adding a sequential total-correctness judgment

$$\frac{R \vdash \{p \wedge B\} C \{p\} \quad \boxed{\vdash [p \wedge B] \text{while}(B)\{C\} [p \wedge \neg B]}}{R \vdash \{p\} \text{while}(B)\{C\} \{p \wedge \neg B\}} \quad (\text{New WHILE rule})$$

prevent *divergences*  
caused by *finite*  
*interference*

- Informal principles to extend a logic for verifying linearizability to verifying obstruction-freedom
  - can reuse the existing proof for linearizability
- A case study: have verified a practical obstruction-free double-ended queue
  - The implementation is from a classic paper, where the concept of obstruction-freedom was proposed for the first time.
  - We prove the implementation satisfies both obstruction-freedom and linearizability.